New trends in system software security

Secappdev 2019

Frank Piessens, February 18, 2019

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Introduction

What is ICT security?

› The field of ICT security addresses the problem of

  ›› *Maintaining **desirable properties** of ICT systems in the presence of **intelligent adversaries** trying to break these properties*

› In practice:

  ›› "Desirable properties" are hard to nail down

  ›› But we recognize security failures when we see them

    ››› Viruses, worms, defacements, data leaks, ransomware, DDOS, jailbreaks, ...

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An important underlying cause: insecure software

› Software implementation vulnerability =

 ›› A defect in software code (a "bug") that can be exploited by an attacker to break some security objective of the software

› Around 100.000 such vulnerabilities listed in the Common Vulnerabilities and Exposures (CVE) list

 ›› Buffer overflows, SQL injection, cross-site scripting, race conditions, side-channel vulnerabilities, information leaks, incomplete access mediation, cross-site scripting, double free, …

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DIRTY COW

Image Tragick

#cloudbleed

4

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Vulnerabilities in system software

› System software (operating systems, low-level libraries, servers, browsers, …) is often programmed in performance-friendly, "close-to-hardware" languages like C / C++

› These languages are infamous for the broad class of *memory management vulnerabilities*

› While many mitigation techniques are deployed, these vulnerabilities still represent a major threat

› Moreover, a vulnerability in system software affects the security of all applications running on the system

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Purpose of this lecture:

› Provide insight in a number of new trends in **system software security**

›› New hardware architectures for the safe execution of C

››› Capability machines

›› New language designs for systems programming, safe by design

››› Rust ownership types

›› [If time: new attacks]

››› [Spectre style attacks]

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Overview of the rest of the talk

System model and attacker model

›› Recap of how C-like languages are executed on standard processors

›› Interactive attacker model

› Memory capabilities for run-time security

› Ownership types for compile-time security

› [The next wave of attacks]

› Conclusions

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System model / attacker model / security objective

› A rigorous study of security requires:

  ›› A **system model**: a model of the system under attack that is sufficiently detailed to explain the attacks one cares about

    ››› Our systems are essentially C programs, but we need to model how compilation works to explain relevant attacks

  ›› An **attacker model**: a precise description of what an attacker can and cannot do

  ›› A **security objective**: either a description of system properties to be maintained, or of attacks/threats to be avoided

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Platform model

› Target platform consists of:

  » A memory of MAX words (addresses 0 .. MAX-1)

    ››› Making abstraction of issues like word-size, padding, …

  » A CPU with

    ››› Registers:

      ›››› PC, x0 (=0), x1(=ra), x2(=sp), x3(=gp), x4,…

    ››› Typical RISC-like instructions

      ›››› Arithmetic/logical/shift

      ›››› Memory access

      ›››› Conditional/unconditional branch

    ››› Instructions can be encoded as words

› Details vary across platforms

Example instruction	Semantics
`add x5,x6,x7`	x5 = x6 + x7
`addi x4,x5,10`	x4 = x5 + 10
`lw x4,50(x5)`	x4 = M[x5 + 50]
`sw x5,30(x4)`	M[x4+30] = x5
`beq x5,x6,12`	if x5==x6 goto PC+12
`jal 12`	x1 = PC+1; goto PC+12
`jalr 10(x5)`	x1 = PC+1; goto x5+10

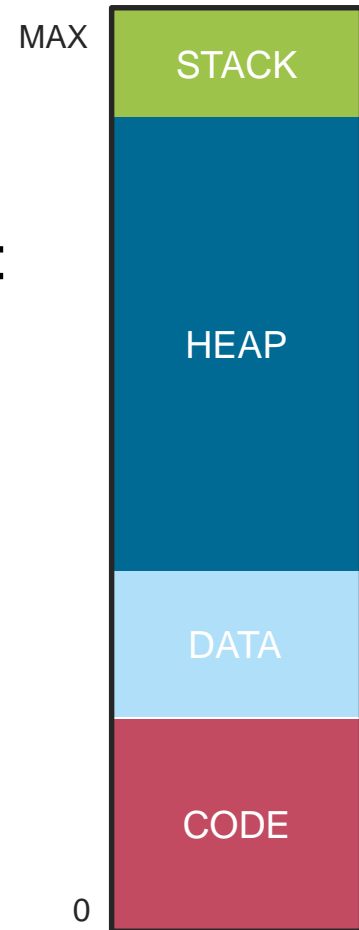KU LEUVEN DistriNet

Source code model

› Simple C-like language

>> Types: char, int, void, pointers (e.g. char*, int**, …), arrays (e.g. char[10])

>> Local and global variables

>>> Array variable is a pointer to the first element of the array

>> Statements and expressions:

>>> Constants, variables, logical and arithmetic expressions, array indexing

>>> If / while / sequencing / blocks / assignment / function calls

>>> Library functions for I/O and memory management:

>>>> getchar(), putchar(),gets(), printf() + other typical C functions for I/O – we will just use getint() and putint()

>>>> malloc() and free()

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Example source program

```
1   void sum(int* r) {
2     int i,result;
3     i = getint(); result = 0;
4     while (i != 0) {
5         result += i;
6         i = getint();
7     }
8     r[0] = result;
9   }
10
11  void main() {
12    int* result = malloc(1);
13    sum(result);
14    putint(result[0]);
15  }
```
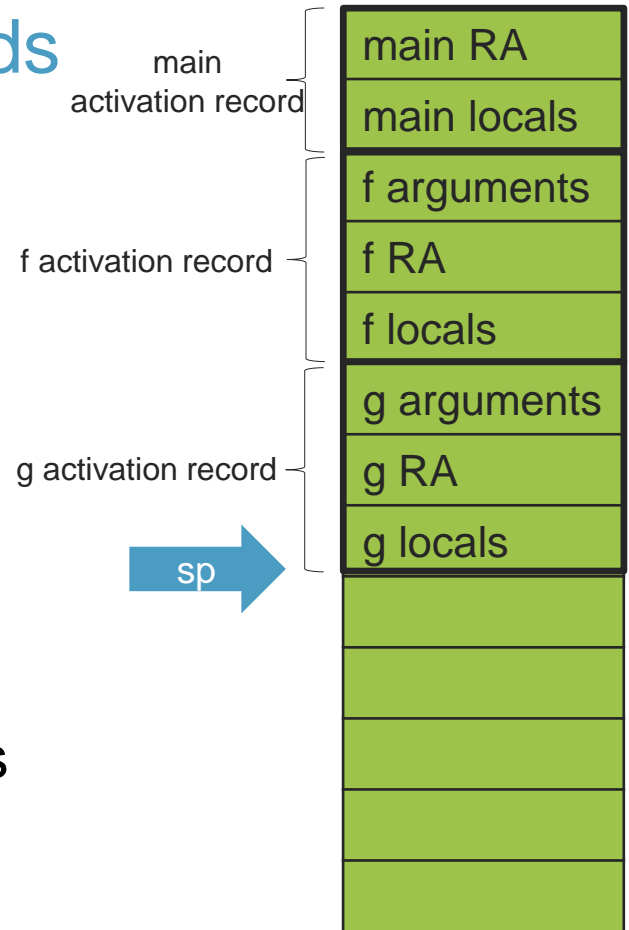
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Compilation: Memory layout

› A compiled program uses memory for 4 purposes:

>› CODE: contains compiled machine code

>› DATA: contains global variables

>› HEAP: contains dynamically allocated program data

>› STACK: contains the call stack that tracks function invocations

MAX

STACK

HEAP

DATA

CODE

0

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Compilation: Stack activation records

main activation record
| main RA |
| main locals |

f activation record
| f arguments |
| f RA |
| f locals |

g activation record
| g arguments |
| g RA |
| g locals |

sp →

› Call stack is a stack of activation records, each containing:

» Call arguments

» Return address

» Space for local variables

› NOTE: many real-world compilation details elided (frame pointer, using registers, …)

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Compilation: malloc() and the heap

HEAPEND

› Simplified malloc() implementation:

```
1  int* malloc(int n) {
2    int* result;
3    if ((((int *) HEAPSTART[0]) + n) >= HEAPEND) return (int *) 0;
4    result = (int *) HEAPSTART[0];
5    HEAPSTART[0] = (int) (result + n);
6    return result;
7  }
```

Free memory

Allocated memory

› Note: many real-world implementation details elided
(supporting free(), supporting virtual memory,…)

HEAPSTART

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Compilation: the CODE section

› Code for every function is compiled separately

  ›› Prologue: allocates space for activation record

  ›› Code for the body

  ›› Epilogue: put result in designated register, clear space for activation record

› We do not show the implementation of I/O

  ›› Could be syscall, instruction, memory mapped, …

code
for
f()
code
for
g()
code
for
main()
code for
malloc()
rt support
code

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Example Compilation

```
void sum(int* r) {
  int i,result;

  i = getint();

  result = 0;
  while (i != 0) {
      result += i;
      i = getint();
  }
  r[0] = result;
}
```

```
sum:
  addi sp,sp,-4     // activation record: arg,ra,i,result
  sw x10, 3(sp)     // save argument in activation record
  sw ra, 2(sp)      // save return address in act record

  jal getint        // call getint()
  sw x10, 1(sp)     // store return value in i

  sub x5, x5, x5    // x5 = 0 (no need to store in memory)

loop:
  beq x10, x0, end  // if (i==0) goto end
  add x5, x5, x10   // x5 += i (still in x10)
  jal getint        // call getint() -> return value in x10
  beq x0,x0,loop    // unconditional jump to start of loop

end:
  lw x6, 3(sp)      // load r in x6
  sw x5, 0(x6)      // r[0] = x5
  lw ra, 2(sp)      // restore return address
  addi sp,sp,4      // remove activation record
  jalr ra           // return
```

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Interactive attacker

› Models attacks that consist of crafting malicious input and learning from output of the program

›› In our system model: attacker gets to see putint() arguments and gets to choose getint() results
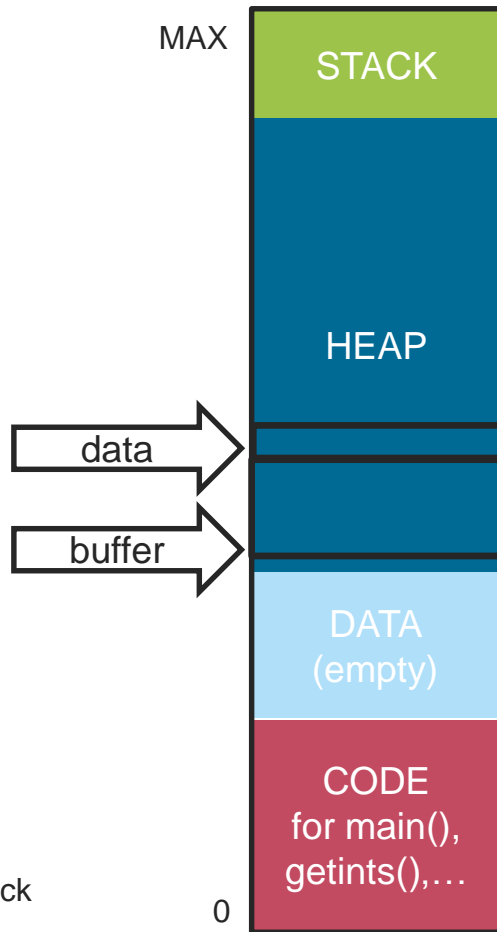
Example attack 1: buffer overwrite

```
1   void main() {
2     int i;
3     int* buffer = malloc(10);
4     int* data = malloc(1);
5     data[0] = 101; // high integrity data
6     getints(buffer);
7     i = 0;
8     while (i < 10) {
9       putint(buffer[i]); i = i + 1;
10    }
11  }
12
13  void getints(int* a) {
14    int i,n;
15    i = 0;
16    n = getint();
17    while (n !=0) {
18      a[i] = n;
19      i = i + 1;
20      n = getint();
21    }
22  }
```

Many variants exist:
- Data-only attack
- Code corruption attack
- Direct code injection attack
- Code reuse (indirect code injection) attack

MAX

| STACK |
| HEAP |

data →

buffer →

| DATA (empty) |
| CODE for main(), getints(),… |

0

18

Example attack 2: buffer over-read

```
1   void main() {
2     int i;
3     int SECRET = 999; //  secret data
4     int* buffer = malloc(10);
5     buffer[0] = 1; buffer[1] = 2; ... // public data in buffer
6
7     i = getint();
8     putint(buffer[i]);
9   }
```

MAX

STACK

999

HEAP

buffer →

DATA
(empty)

CODE
for main(),
…

0

These attacks can leak:
- Application secrets (e.g. keys)
- Secrets that enable other attacks (e.g. ASLR)

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Other vulnerabilities

› The example attacks exploited *spatial* memory vulnerabilities

› But other kinds of software bugs can also lead to memory reads or writes that are not allowed:

›› Temporal memory vulnerabilities

›› Uninitialized variables

›› Variadic function misuse

›› …

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Overview of the rest of the talk

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›› Interactive attacker model

Memory capabilities for run-time security

› Ownership types for compile-time security

› [The next wave of attacks]

› Conclusions

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Capability-machines

› Key idea:

›› Pointers (addresses) are NOT integers.

›› Pointers are **capabilities**:

››› They come with a bound on what you can do with that pointer.

››› The entire machine is designed to ensure that capabilities are a **secure** bound on what you can do

› Capabilities are an old security mechanism, studied both at the machine code / OS level, as well as on the PL level

›› We will just discuss the simplest machine-level variant here

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Capabilities

› A *memory capability* is a hardware "fat pointer"

Base	End	Offset	Metadata

› For simplicity, we assume it can be represented within one word

Platform model: CPU extensions/modifications

› A CPU with:

  ›› Standard registers:

    ››› x0 (=0), x1, x2,…

  ›› Capability registers:

    ››› PCC (program counter capability)

    ››› c0 (=spc), c1 (=rac), c2(=gdc), c3, …

  ›› Modified and new instructions

    ››› Memory access must be through a capability

    ››› Jumps must be to a capability

    ››› Instructions to compute derived capabilities

      ›››› These must **reduce** the authority of the capability

    ››› Instructions to inspect capabilities

    ››› **All instructions check capability constraints**

Example instruction	Semantics
`clw x4,50(c5)`	x4 = M[c5 + 50]
`csw x5,30(c4)`	M[c4+30] = x5
`cjalr 10(c5)`	c1 = PCC+1; PCC = c5 +10
`csetbounds c1,c2,5`	c1.base = c2.offset c1.end = c2.offset + 5 c1.offset = 0 c1.metadata = c2.metadata
`cgetbase x5,c3`	x5 = c3.base

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Platform model: memory extensions

› Every memory word has an associated *tag*

›› Set when a capability is stored in that word

›› Cleared whenever a non-capability value is stored

```
csw c5,30(c4)     // store c5 in memory
…
[csw x4,30(c4)]   // OPTIONALLY: store an int
                  // This would clear the tag
…
clw c5,30(c4)     // load c5 from memory again
```

0

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Capabilities are *unforgeable*

› Guarded manipulation

  ›› Instructions that modify a capability can only reduce their authority

     ››› Increase base or reduce end

     ››› Move offset around between base and end

     ››› Reduce permissions

› Tagged memory

  ›› Capabilities can be stored in memory and copied around, but are protected by a *tag*

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Compilation: Memory layout

› Dedicated processor registers:

» spc: stack pointer capability

» gdc: global data capability

» pcc: program counter capability

» malloc() holds a capability to the heap

and hands out sub-capabilities of appropriate size

MAX

STACK

HEAP

DATA

CODE

0

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Compilation: malloc() and the heap

› malloc() pseudo-implementation:

```
1   int* heap_cap;
2   int* mmalloc(int n) {
3     int* result;
4     if (heap_cap.offset + n) >= heap_cap.end) return (int *) 0;
5     result = csetbounds(heap_cap, n);
6     heap_cap.offset  = heap_cap.offset + n;
7     return result;
8   }
```

heap_cap

p2

p1

Example Compilation

```
void sum(int* r) {
  int i,result;

  i = getint();

  result = 0;
  while (i != 0) {
      result += i;
      i = getint();
  }
  r[0] = result;
}
```

```
sum:
  cincoffset csp,csp,-4 // activation record: arg,ra,i,result
  csw c10, 3(csp)        // save argument in activation record
  csw cra, 2(csp)        // save return address in act record

  jal getint             // call getint() (rel jump to PCC)
  csw x10, 1(sp)         // store return value in i

  sub x5, x5, x5         // x5 = 0 (no need to store in memory)
loop:
  beq x10, x0, end       // if (i==o) goto end (rel branch)
  add x5, x5, x10        // x5 += i (still in x10)
  jal getint             // call getint() -> return value in x10
  beq x0,x0,loop         // unconditional jump to start of loop

end:
  clw c6, 3(sp)          // load r in c6 (must be cap register!)
  csw x5, 0(c6)          // r[0] = x5 (store through capability)
  clw cra, 2(sp)         // restore return address
  cincoffset csp,csp,4 // remove activation record
  cjalr cra              // return
```

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Memory capabilities for safe compilation of C

› Memory capabilities can represent C pointers, and enforce spatial memory safety at run time

  ›› Within the interactive attacker model

› This is relatively simple to prove for simplified settings such as the one we considered in this talk

  ›› CAVEAT: reading uninitialized memory

› For a recent *realistic* prototype, see for instance:

  ›› David Chisnall, et al. *Beyond the PDP-11: Processor support for a memory-safe C abstract machine*, (ASPLOS 2015)

  ›› This paper considers many of the challenges involved in bringing this to real-world C

› The main challenge still faced by capability systems is *revocation* (i.e. efficient implementations of free())

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Conclusions

› Memory capabilities are a useful hardware primitive to build secure C compilers

› Hardware-supported capabilities are becoming more mainstream

  ›› The CHERI project: https://www.cl.cam.ac.uk/research/security/ctsrd/cheri/

  ›› Arm is working with the CHERI team to bring these ideas into the Arm architecture:

    ››› https://community.arm.com/company/b/blog/posts/supporting-the-uk-in-becoming-a-leading-global-player-in-cybersecurity

› And we are not even using the full power of capabilities yet

  ›› In particular, a capability processor satisfies a *monotonicity* property:

    ››› The set of memory addresses that a program has access to (directly or indirectly), can only shrink over time.

  ›› This makes it possible to *share* a memory address space between distrusting program components providing strong compartmentalization guarantees

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Overview of the rest of the talk

› System model and attacker model

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› Memory capabilities for run-time security

Ownership types for compile-time security

› [The next wave of attacks]

› Conclusions

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Memory safety

› An important reason why C programs have exploitable security vulnerabilities is because of unsafe memory accesses

  ›› The program contains a bug (e.g. missing bounds check) such that the compiled program performs a memory access (read or write) that an attacker can control

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Essentially, only 4 ways things can go wrong

› **Spatial memory safety errors**: a blob of allocated memory is accessed out of bounds

› **Temporal memory safety errors**: a blob of memory is accessed after it has been deallocated

› **Pointer forging**: creating an invalid pointer value

›› By invalid casts

›› By use of uninitialized memory

› **Unsafe primitive API functions**:

›› Like C's printf() function

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Spatial memory safety

› Examples: indexing an array, indexing a struct, pointer arithmetic

```
void f1(int a[]) {
    a[5] = 10;
}

void f2(int *a) {
    *(a+5) = 10;
}
```

```
struct S {
    int x;
    int y; };

void f3(struct S p) {
    p.x = 20;
}
```

› How could the compiler protect against spatial memory safety errors?

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Enforcing spatial memory safety

› Through type checking for structs and arrays with statically known bounds

 » E.g. Java type system will make sure that you can not access a non-existing field of an object

› Through run-time bounds checking otherwise

 » E.g. Java throws ArrayIndexOutOfBoundsException

 » E.g. "Fat" pointers in C or C++

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Temporal memory safety

› How long are pointers valid?
  This depends on how the pointer is created.

```
int c;

int* f(int x) {
    int i;
    int *p1 = &c;
    int *p2 = malloc(sizeof(int));
    int *p3 = &x;
    int *p4 = &i;

    return p1; // or p2? or p3? or p4?
}
```

A simple example

```c
typedef struct  {
    int len;
    int cap;
    int* data;
} vec;

vec newvec() {
    vec v;
    v.len = 0;
    v.cap = 2;
    v.data = malloc(2*sizeof(int));
    return v;
}

void push(vec* v, int i) {
    if (v->len >= v->cap) {
        v->cap *= 2;
        int *new = malloc(v->cap * sizeof(int));
        memcpy(new,v->data, v->len * sizeof(int));
        free(v->data);
        v->data = new;
    }
    v->data[v->len++] = i;
}
```

```c
void printvec(vec v) {
    int i;
    for (int i = 0; i < v.len; i++) {
        printf("%d\n", v.data[i]);
    }
}

int* get(vec* v, int i) {
    return v->data + i;
}

void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```
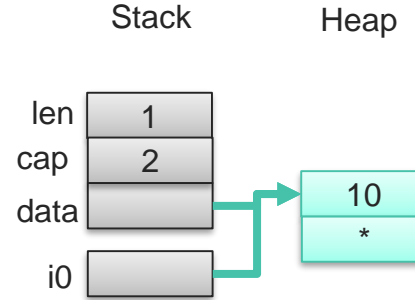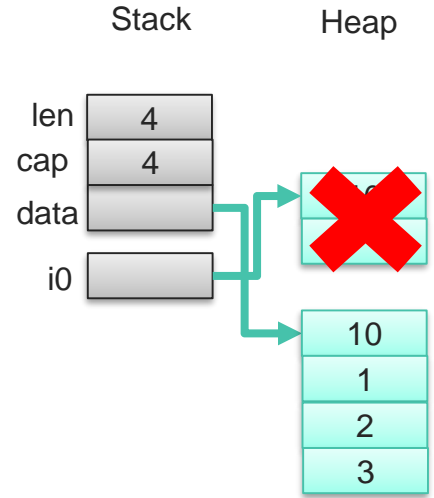
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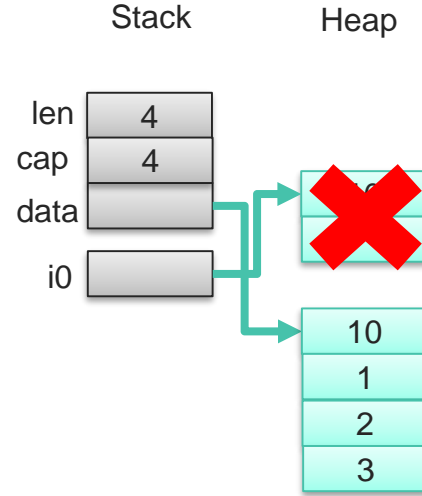
A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```

Stack

Heap

len | 0
cap | 2
data |

*

*

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A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```

Stack   Heap

len   1
cap   2
data   0
              *

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A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```
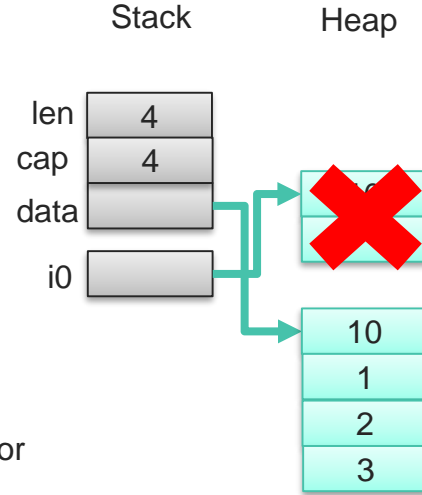
Output:
0

Stack   Heap

len | 1 |
cap | 2 |
data | | → | 0 |
                | * |

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A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```
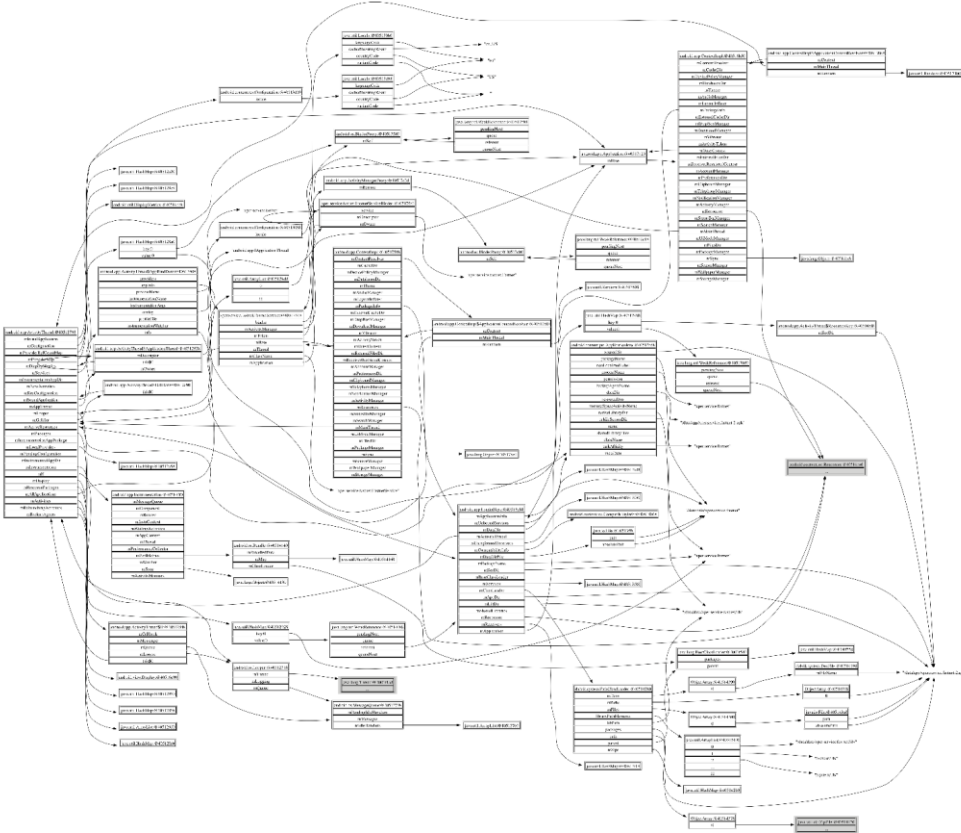
Output:
0

Stack   Heap

len   1
cap   2
data   10
                *
i0

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A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```

Output:
0
10

Stack

Heap

len 1
cap 2
data   10
           *
i0

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A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```

Output:
0
10

A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```

Output:
0
10
10
1
2
3

Stack   Heap

len   4
cap   4
data
i0

10
1
2
3

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A simple example

```
void main() {
    vec v = newvec();
    int i;
    push(&v,0);
    printvec(v);
    int* i0 = get(&v,0); *i0 = 10;
    printvec(v);
    for (i = 1; i < 4; i++) push(&v,i);
    printvec(v);
    *i0 = 20;
    printvec(v);
}
```

Output:
0
10
10
1
2
3

Temporal memory safety error

Stack   Heap

len   4

cap   4

data

i0

10
1
2
3

Real heap looks more complicated…

Enforcing temporal memory safety

› Allocate everything on the heap, and do **garbage collection**:

   ›› Programmer can not do explicit deallocation

      ››› I.e. no free()

   ›› At regular intervals, the program will be halted and the run-time system will clean up unused memory

      ››› Basic idea: check what memory is reachable from the current program state, and deallocate all the rest

      ››› Many different strategies to implement this with different pros and cons

› Important disadvantages for systems programming:

   ›› Less precise control over memory

   ›› Unpredictable timing

Enforcing temporal memory safety

› New approach: **ownership types** and **borrowing**

› Basic idea:

›› There is at all times a unique **owning** pointer to each allocated blob of memory

›› Memory is deallocated when the owning pointer disappears

››› Because it goes out of scope

››› Or because it is overwritten

››› Or because it was part of a data structure that is being deallocated

› We discuss the implementation of this idea in **Rust**

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Memory management in Rust

› Programmer controls:

   ›› At what time memory is allocated

   ›› And where it is allocated (stack / heap)

› Deallocated when owner goes out of scope

```rust
fn main() {
    let x = 1; // allocated on the stack
    let y = Box::new(1); // allocated on the heap
}
```

Stack   Heap

x [1]   [1]

y [   ]

No use after free is possible

› There was only a single pointer, and it has gone out of scope

```
fn main() {

    {
    let x = Box::new(1);      // alloc x
    println!("x = {}", *x);
    }                         // free x
// ERROR: println!("x = {}", *x);
}
```

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Move semantics

› Pointers are not copied but **moved**

```
fn main() {

let mut y = Box::new(2);

  {
  let x = Box::new(1);
  println!("x = {}", *x);
  y = x;
  // ERROR: println!("x = {}", *x);
  }

println!("y = {}", *y);
}
```
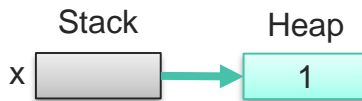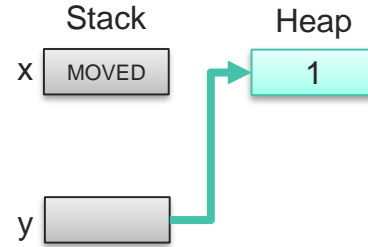
Stack   Heap

y [   ] → [2]

Move semantics

› Pointers are not copied but **moved**

```rust
fn main() {

let mut y = Box::new(2);

 {
let x = Box::new(1);
println!("x = {}", *x);
 y = x;
 // ERROR: println!("x = {}", *x);
 }

println!("y = {}", *y);
}
```

Stack   Heap

x [   ] → [1]
y [   ] → [2]

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Move semantics

› Pointers are not copied but **moved**

```
fn main() {

let mut y = Box::new(2);

    {
    let x = Box::new(1);
    println!("x = {}", *x);
 →  y = x;
    // ERROR: println!("x = {}", *x);
    }

println!("y = {}", *y);
}
```

Stack   Heap

x [MOVED]   ┌→ [1   ]
y [   ]───┘

Move semantics

› Pointers are not copied but **moved**

›› Hence: there is always a **unique** owning pointer

```rust
fn main() {

let mut y = Box::new(2);

 {
 let x = Box::new(1);
 println!("x = {}", *x);
 y = x;
 // ERROR: println!("x = {}", *x);
 }

println!("y = {}", *y);
}
```


Stack   Heap

y   1

Pointers move into functions too

› Ownership moves from argument to formal parameter
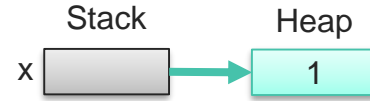
› So when is the allocated memory freed in the program below?

```rust
fn main() {
    let x = Box::new(1);
    println!("x = {}", *x);
    f(x);
    // ERROR: println!("x = {}", *x);
}

fn f(y : Box<i32>) {
    println!("y = {}", *y);
}
```

Stack   Heap

x [   ] → [1]

Pointers move into functions too

› Ownership moves from argument to formal parameter

› So when is the allocated memory freed in the program below?

```rust
fn main() {
    let x = Box::new(1);
    println!("x = {}", *x);
    f(x);
    // ERROR: println!("x = {}", *x);
}

fn f(y : Box<i32>) {
    println!("y = {}", *y);
}
```

Stack

x | MOVED

y |

Heap

1

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Pointers move into functions too

› Ownership moves from argument to formal parameter

› So when is the allocated memory freed in the program below?

```rust
fn main() {
    let x = Box::new(1);
    println!("x = {}", *x);
    f(x);
    // ERROR: println!("x = {}", *x);
}

fn f(y : Box<i32>) {
    println!("y = {}", *y);
}
```

Stack   Heap

x | MOVED |

Pointers can also move into Boxes and structs

```rust
fn main() {
    let mut x = Box::new(1);
    let mut y = Box::new(x);
    let mut z = Box::new(y);
    println!("Val:{}",***z);
}
```

Stack   Heap

x [   ] → [1]

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Pointers can also move into Boxes and structs

```rust
fn main() {
    let mut x = Box::new(1);
    let mut y = Box::new(x);
    let mut z = Box::new(y);
    println!("Val:{}",***z);
}
```

Stack Heap

x MOVED
y

1

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Pointers can also move into Boxes and structs

```rust
fn main() {
    let mut x = Box::new(1);
    let mut y = Box::new(x);
    let mut z = Box::new(y);
    println!("Val:{}",***z);
}
```

Stack | Heap

x [MOVED]   [1]

y [MOVED]

z [   ]

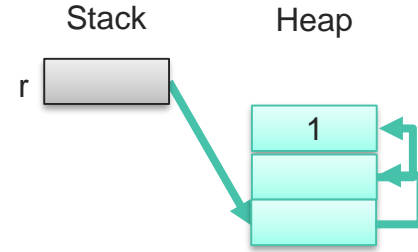# Moving into a box can extend life


```rust
fn main() {

    let r = f();
    println!("Val:{}", ***r);
}

fn f() -> Box<Box<Box<i32>>> {
    let x = Box::new(1);
    let y = Box::new(x);
    let z = Box::new(y);
    println!("Val:{}", ***z);
    return z;
}
```

Moving into a box can extend life

```rust
fn main() {

    let r = f();
    println!("Val:{}", ***r);
}

fn f() -> Box<Box<Box<i32>>> {
    let x = Box::new(1);
    let y = Box::new(x);
    let z = Box::new(y);
    println!("Val:{}", ***z);
    return z;
}
```

Stack   Heap

r   -

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Moving into a box can extend life

```rust
fn main() {

    let r = f();
    println!("Val:{}", ***r);
}

fn f() -> Box<Box<Box<i32>>> {
    let x = Box::new(1);
    let y = Box::new(x);
    let z = Box::new(y);
    println!("Val:{}", ***z);
    return z;
}
```

Stack

r	-
x	MOVED
y	MOVED
z	

Heap

1

64

Moving into a box can extend life

```rust
fn main() {

    let r = f();
    println!("Val:{}", ***r);
}

fn f() -> Box<Box<Box<i32>>> {
    let x = Box::new(1);
    let y = Box::new(x);
    let z = Box::new(y);
    println!("Val:{}", ***z);
    return z;
}
```

Stack   Heap

r

1

Enforcing unique ownership simplifies the heap

› The heap is a forest (set of trees), with allocated blobs of memory as nodes, and owning references as arrows.

› Roots of the trees are on the stack:

›› local variables of Box type

› If a local variable goes out of scope, that tree gets deallocated

›› We know that there are no other owners, because of uniqueness of ownership

› Uniqueness of ownership is maintained with the move semantics of pointers

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Borrowing

› Move semantics is sometimes too limiting / annoying

```rust
fn main() {
  let mut x = Box::new(1);
  print(x);
  *x = 2;              ⬅ ERROR
  print(x);
}

fn print(y:  Box<i32>) {
  println!("Value:{}", *y);
}
```
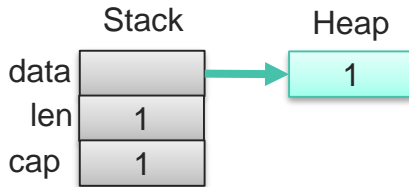
› Rust supports "borrowing" of references to address this

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Borrowing

```rust
fn main() {
 let mut x = Box::new(1);
 print(&x);
 *x = 2;
 print(&x);
 }

fn print(y: &Box<i32>) {
 println!("Value: {}", **y);
}
```

Stack   Heap

x [   ] → [1]

Borrowing

```rust
fn main() {
 let mut x = Box::new(1);
 print(&x);
 *x = 2;
 print(&x);
 }

fn print(y: &Box<i32>) {
 println!("Value: {}", **y);
}
```

Stack   Heap

x [_____] → [1]

y [_____]

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Borrowing

```
fn main() {
  let mut x = Box::new(1);
  print(& *x);
  *x = 2;
  print(& *x);
}

fn print(y:  &i32) {
  println!("Value:{}", *y);
}
```

Stack   Heap

x [   ] → [1]

y [   ] ──┘

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Borrowing rules

› To avoid introducing temporal safety errors, borrowing and ownership follow some rules:

 ›› The *lifetime* of a borrow should always be included in the lifetime of the owner from which it is borrowed

  ››› Otherwise, if the owner dies, the borrowed reference would be dangling

```rust
fn main() {
  let mut x = Box::new(1);
  let mut y = &x;
  {
   let mut z = Box::new(2);
   y = &z;
  }
}
```

```
6:9: 6:10 error: `z` does not live long enough
6     y = &z;
          ^
```
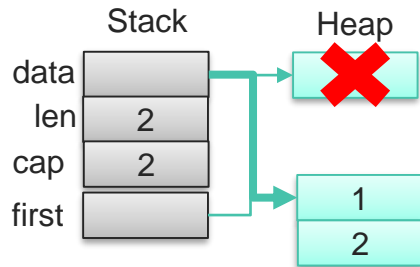
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Borrowing should also forbid mutation

```rust
fn main() {
 let mut vec = Vec::new();
 vec.push(1);
 let first = &vec[0];
 // ERROR: vec.push(2);
 println!("{}", *first);
}
```

Stack   Heap

data [ ] ──→ [1]
len   [1]
cap   [1]

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Borrowing should also forbid mutation

```rust
fn main() {
 let mut vec = Vec::new();
 vec.push(1);
 let first = &vec[0];
 // ERROR: vec.push(2);
 println!("{}", *first);
}
```

Stack

Heap

data

len | 1

cap | 1

first

1

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Borrowing should also forbid mutation

```rust
fn main() {
 let mut vec = Vec::new();
 vec.push(1);
 let first = &vec[0];
 // ERROR: vec.push(2);
 println!("{}", *first);
}
```

Stack | Heap

data → 1

len 2

cap 2

first → 1
2

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Borrowing should also forbid mutation

```rust
fn main() {
 let mut vec = Vec::new();
 vec.push(1);
 let first = &vec[0];
 // ERROR: vec.push(2);
 println!("{}", *first);
}
```


Stack   Heap

data   ❌
len   2
cap   2
first   1
  2

Borrowing rules

› Rust supports borrowing:

 »» Either: an arbitrary number of immutable references

 »» Or: a single mutable reference

› To ensure safety, Rust ensures:

 »» Modification through the owner is disallowed while borrows are outstanding

 »» Lifetimes of borrowed references are always strictly included in the lifetime of the owner

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Summary: Ownership and borrowing

› Together these concepts:

  ›› Can guarantee temporal memory safety statically

    ››› By ruling out simultaneous aliasing + mutation

  ›› Allow relatively flexible pointer manipulating programs

› Many advantages:

  ›› No need for a run-time (no garbage collection)

  ›› Also helps in avoiding data races (concurrency errors)

› Some disadvantages:

  ›› Non-trivial to use

  ›› Not as flexible as C

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The Rust programming language

› Is one of the fastest growing languages at the moment

› Since Firefox 48 (August 2016), there is Rust code in Firefox

› The language has many other interesting features that we did not discuss

›› Pattern matching

›› Traits

›› Generics

›› …

› See:

›› https://www.rust-lang.org/

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Comparison

› Java/C#/JavaScript/…

  ›› Runtime = virtual machine + JIT compiler + GC + …

  ›› Garbage collection can induce substantial latency

    ››› "Stop-the-world"

› Go

  ›› Runtime = GC

  ›› Low-latency garbage collection

    ››› Focus on GC algorithms that can keep the program running

› Rust

  ›› "Runtime" = just a set of libraries

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Overview of the rest of the talk

› System model and attacker model

  ›› Recap of how C-like languages are executed on standard processors

  ›› Interactive attacker model

› Memory capabilities for run-time security

› Ownership types for compile-time security

[The next wave of attacks]

› Conclusions

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Introduction

› In 2018, micro-architectural attacks have come of age:

  ›› Meltdown breaks user/kernel isolation

  ›› Spectre breaks several isolation boundaries that software security fundamentally relies on

  ›› Foreshadow breaks SGX enclave isolation

› Hardware and system software vendors are scrambling to address these attacks

References:
Paul Kocher et al. *Spectre Attacks: Exploiting Speculative Execution*, IEEE S&P 2019
Moritz Lipp et al. *Meltdown: Reading Kernel Memory from User Space*, USENIX Security Symposium 2018
Jo Van Bulck et al. *Foreshadow: Extracting the Keys to the Intel SGX Kingdom with Transient Out-of-Order Execution*, USENIX Security Symposium 2018

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Attacker model: Shared platform attacker

› The attacker can run code on the same platform where victim code is running.

› The objective of the attacker is to learn more about the victim than what one can learn through intended communication interfaces.
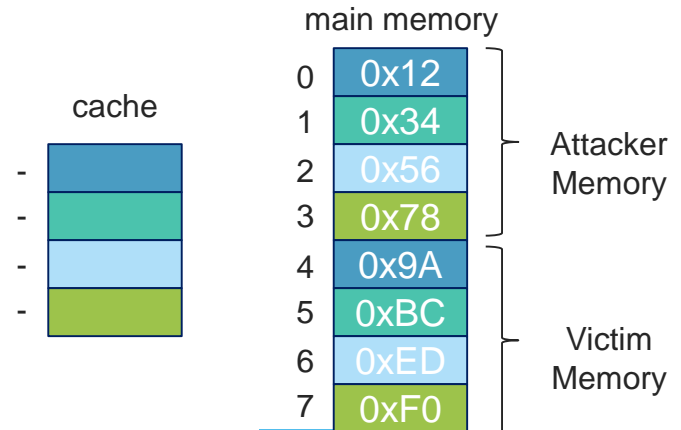
Micro-architectural attacks

› The attacker learns information by manipulating and observing the victim program's use of shared platform resources such as the cache, the branch predictor, …
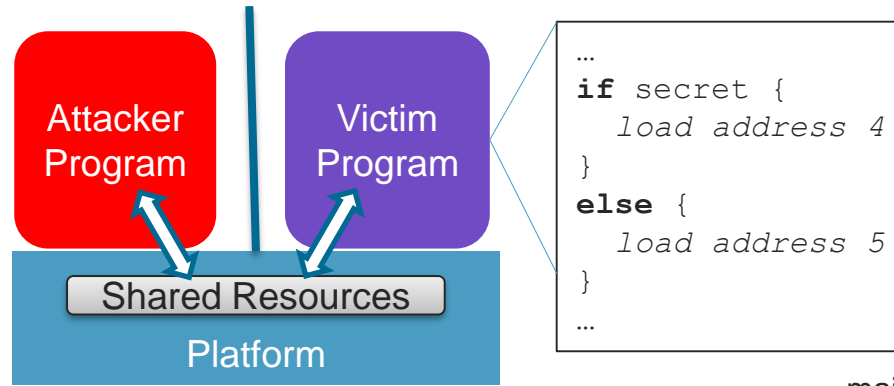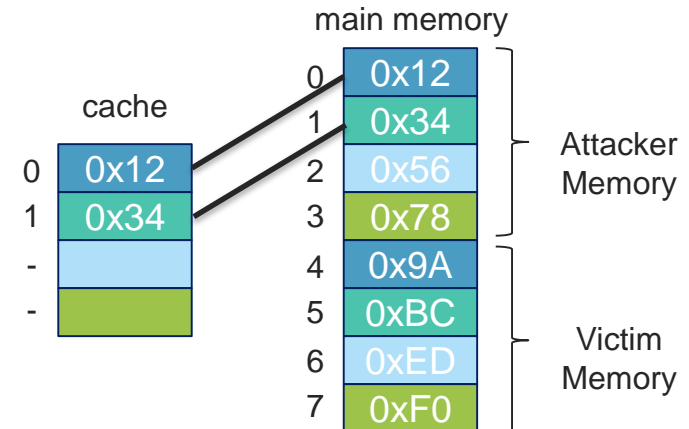
Side-channels: a simple example of a cache-attack

Attacker Program

Victim Program

```
…
if secret {
    load address 4
}
else {
    load address 5
}
…
```

Shared Resources

Platform

main memory

cache

CPU

› The shared resources between attacker and victim program include a direct-mapped cache

0	0x12
1	0x34
2	0x56
3	0x78

Attacker Memory

4	0x9A
5	0xBC
6	0xED
7	0xF0

Victim Memory

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Side-channels: a simple example of a cache-attack


```
…
if secret {
    load address 4
}
else {
    load address 5
}
…
```

› The shared resources between attacker and victim program include a direct-mapped cache

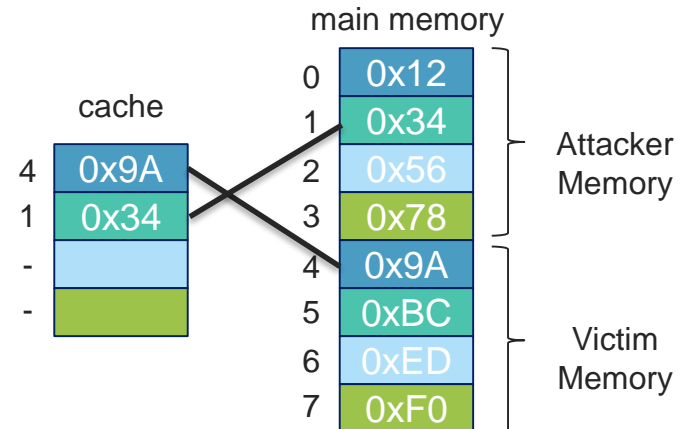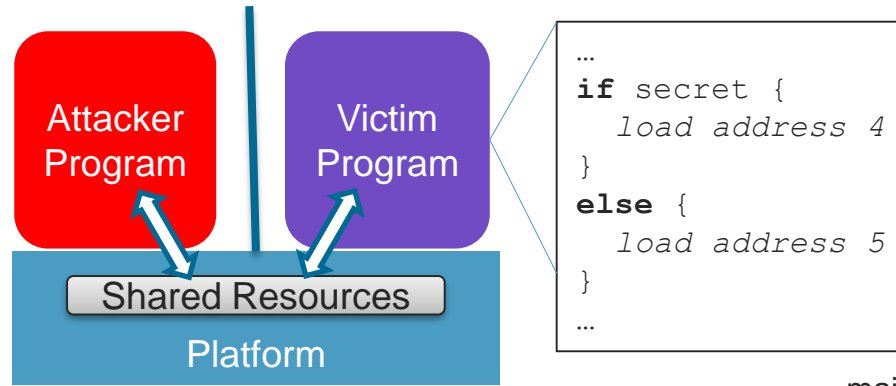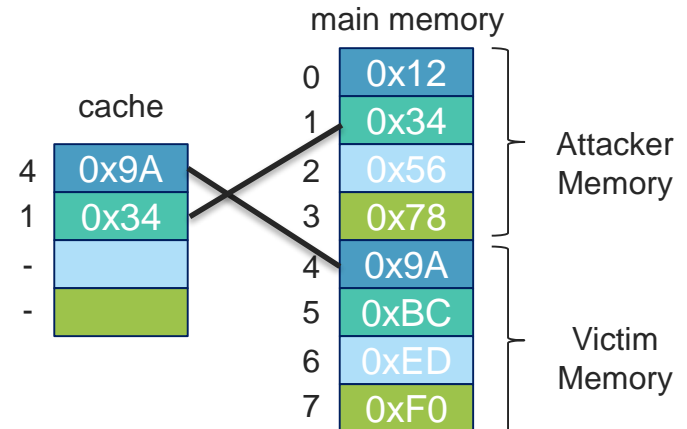›› First the attacker program runs and occupies the first two cache lines

Side-channels: a simple example of a cache-attack

› The shared resources between attacker and victim program include a direct-mapped cache

 ›› First the attacker program runs and occupies the first two cache lines

 ›› Next the victim program runs and performs **secret-dependent** memory accesses

Side-channels: a simple example of a cache-attack


```
...
if secret {
    load address 4
}
else {
    load address 5
}
...
```

› The shared resources between attacker and victim program include a direct-mapped cache

›› First the attacker program runs and occupies the first two cache lines

›› Next the victim program runs and performs **secret-dependent** memory accesses

›› Finally, attacker measures duration of an access to address 0

87

Cache attacks

› Cache-based side-channel attacks have been understood for quite a while

› Countermeasures exist:

›› At the hardware level, e.g. cache partitioning

›› At the software level, e.g. the crypto constant time model
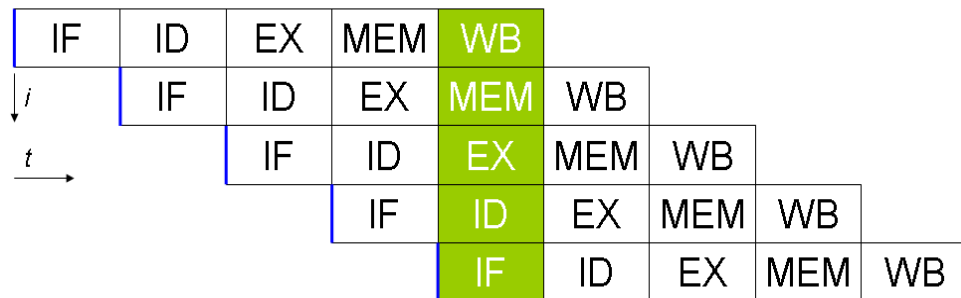
Qian Ge, Yuval Yarom, David Cock, Gernot Heiser: A survey of microarchitectural timing attacks and countermeasures on contemporary hardware. J. Cryptographic Engineering (2018)

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Speculative execution attacks

› Speculative execution attacks amplify the impact of existing side-channels **by giving the attacker control over the sending side of the channel** too

› The key observations are:

›› Processors are pipelined and sometimes execute instructions *speculatively*

››› No architectural effects are visible until instruction is committed

›› Speculatively executed instructions *also impact the micro-architectural state*

›› The attacker *can influence what instructions get executed speculatively*

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Speculative execution

› All major processors support
speculative execution

  ›› Processor implementations are pipelined

  ›› To keep the hardware busy, instructions
are executed *out-of-order* and
speculatively

  ›› No visible *architectural* effects of
speculatively executed instructions – but
there are persistent micro-architectural
effects

IF	ID	EX	MEM	WB				
i	IF	ID	EX	MEM	WB			
t		IF	ID	EX	MEM	WB		
			IF	ID	EX	MEM	WB	
				IF	ID	EX	MEM	WB

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A simple example of a speculative execution attack

attacker code

```
// train the branch predictor
process(0); process(0); …
// prime the cache
for (j=0; j<4; j++) z = a[j];
// attack!
process(size);
// measure access time to a[j] for all j
// slowest j is the SECRET
```
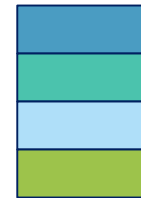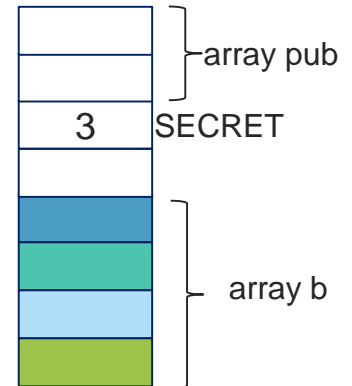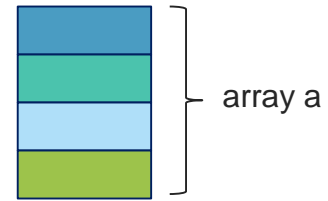
attacker memory

array a

cache

victim memory

victim code

array pub

3   SECRET

```
void process(int i) {
  int y;
  if (i < size) y = b[pub[i]];
}
```

array b

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A simple example of a speculative execution attack

attacker code

```
// train the branch predictor
process(0); process(0); …
// prime the cache
for (j=0; j<4; j++) z = a[j];
// attack!
process(size);
// measure access time to a[j] for all j
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```
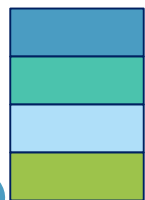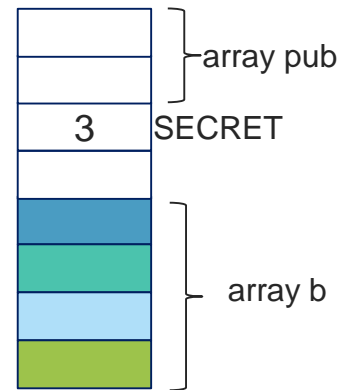
attacker memory

array a

cache

victim memory

array pub

3   SECRET

array b

victim code

Branch predictor learns that usually then branch is taken

```
void process(int i) {
  int y;
  if (i < size) y = b[pub[i]];
}
```

KU LEUVEN DistriNet
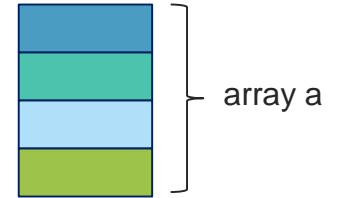
A simple example of a speculative execution attack

attacker code

```
// train the branch predictor
process(0); process(0); …
// prime the cache
for (j=0; j<4; j++) z = a[j];
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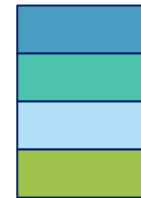
victim code

```
void process(int i) {
  int y;
  if (i < size) y = b[pub[i]];
}
```

attacker memory

array a

cache

victim memory

array pub

3   SECRET

array b

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A simple example of a speculative execution attack

attacker code

```
// train the branch predictor
process(0); process(0); …
// prime the cache
for (j=0; j<4; j++) z = a[j];
// attack!
process(size);
// measure access time to a[j] for all j
// slowest j is the SECRET
```

victim code

```
void process(int i) {
  int y;
  if (i < size) y = b[pub[i]];
}
```
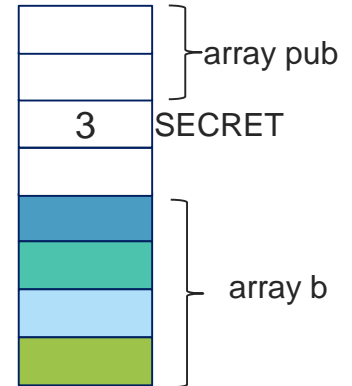
attacker memory

array a

cache

victim memory
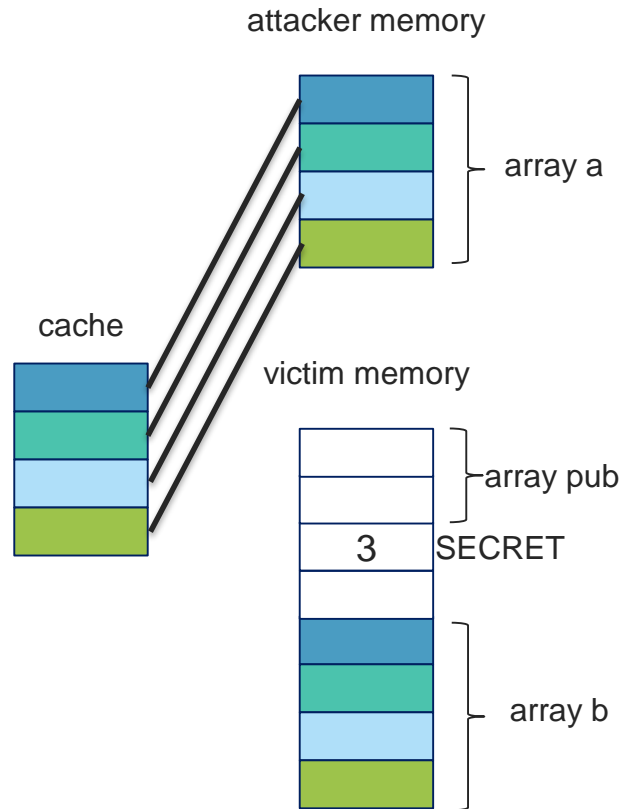
array pub

3   SECRET

array b

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A simple example of a speculative execution attack

attacker code

```
// train the branch predictor
process(0); process(0); …
// prime the cache
for (j=0; j<4; j++) z = a[j];
// attack!
process(size);
// measure access time to a[j] for all j
// slowest j is the SECRET
```

victim code

```
void process(int i) {
  int y;
  if (i < size) y = b[pub[i]];
}
```
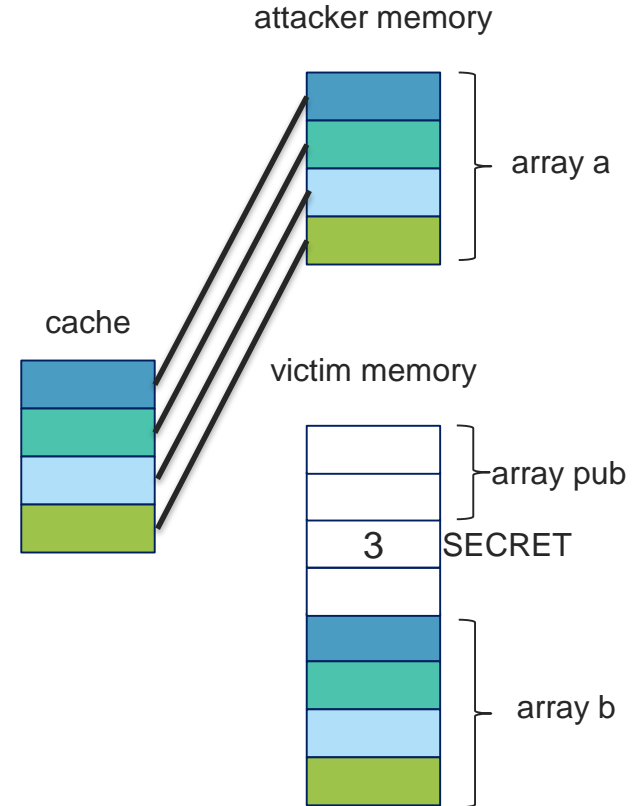
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CPU speculatively executes the then branch

victim code

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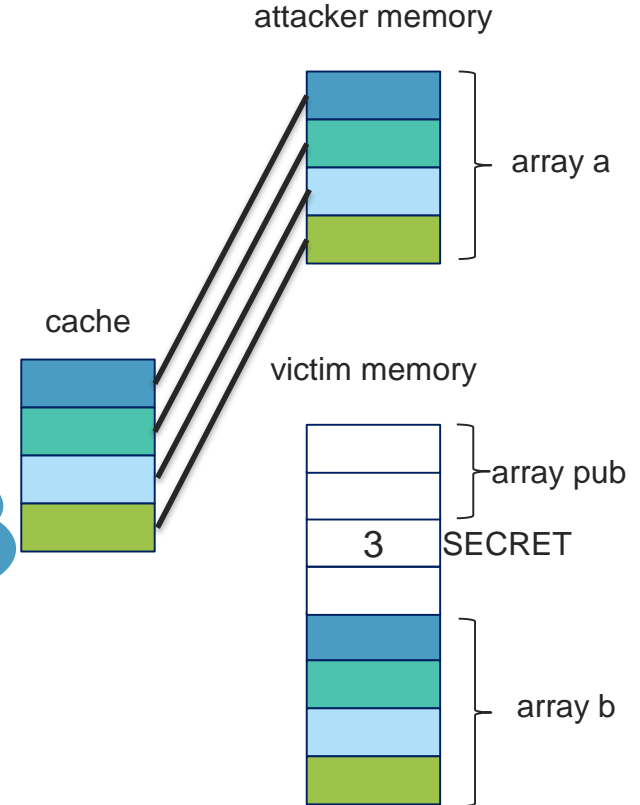
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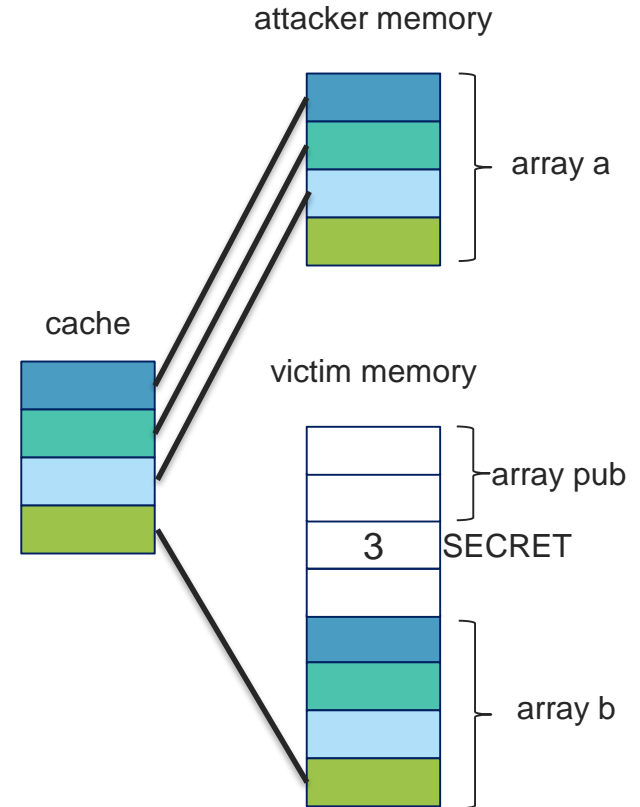
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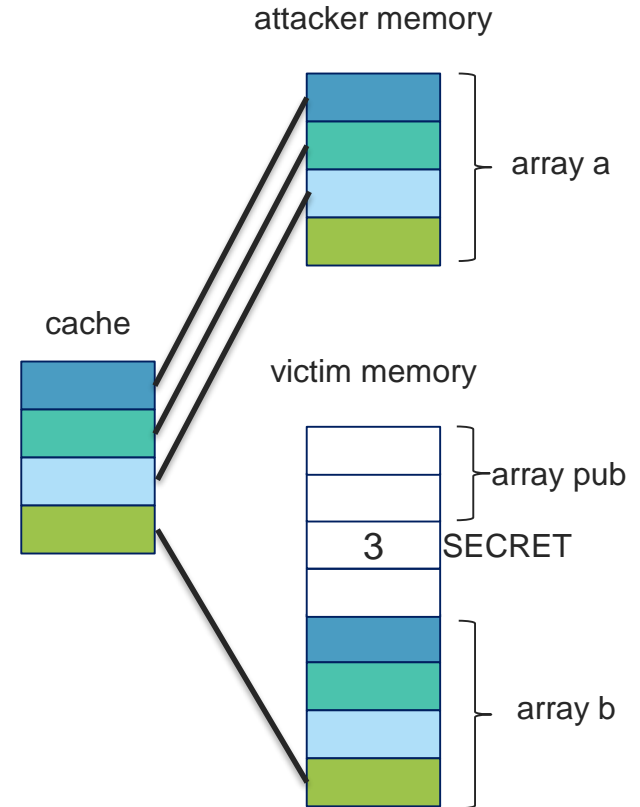
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Speculative execution attacks

› This was a simplified Spectre Variant 1 attack

  ›› Many other variants exist

  ›› Meltdown/Foreshadow style attacks are similar but rely on the micro-architectural effects of out-of-order code execution that leads to an access control exception

› Note the **devastating** nature of this kind of attack

  ›› on any kind of software-enforced confidentiality

  ›› on any kind of hardware-enforced confidentiality where hardware resources are shared over protection boundaries

› Meltdown and Foreshadow are related attacks that exploit the fact that a processor may do speculative execution beyond a faulting instruction

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Overview of the rest of the talk

› System model and attacker model

   ›› Recap of how C-like languages are executed on standard processors

   ›› Interactive attacker model

› Memory capabilities for run-time security

› Ownership types for compile-time security

› [The next wave of attacks]

Conclusions

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Conclusions

› System software plays a key role in ICT security

›› Vulnerabilities in system software impact all applications on the system

›› The boundaries of system software are fuzzy: your application likely relies on system software libraries

› System software is a clear example of the typical attacker-defender race

›› We are currently witnessing the transition to a new wave of attacks …

›› … as well as significant progress with closing the previous wave

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